

MATH 5061 Lecture 7 (Mar 3)

[Problem Set 4 posted, due on Mar 17.]

Recall: $(M^n, g^{\langle, \rangle}) \rightsquigarrow$ Connection $\nabla \rightsquigarrow$ Curvature R

$$R(X, Y)Z := \nabla_Y \nabla_X Z - \nabla_X \nabla_Y Z + \nabla_{[X, Y]} Z$$

$$\Leftrightarrow \underbrace{R(X, Y, Z, W)}_{(0,4)\text{-tensor}} := \langle R(X, Y)Z, W \rangle \quad \forall X, Y, Z, W \in T(TM)$$

In local coord. of M , say (x^1, \dots, x^n) , let $\partial_i := \frac{\partial}{\partial x^i}$

$$g_{ij} = \langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \rangle = \langle \partial_i, \partial_j \rangle$$

$$\Gamma_{ij}^k = \frac{1}{2} g^{kl} (\partial_i g_{lj} + \partial_j g_{il} - \partial_l g_{ij})$$

Compute $R(\partial_i, \partial_j, \partial_k, \partial_l) =: R_{ijkl}$

$$\nabla_{\partial_j} \nabla_{\partial_i} \partial_k = \nabla_{\partial_j} (\Gamma_{ik}^l \partial_l) = (\partial_j \Gamma_{ik}^s) \partial_s + \Gamma_{ik}^l \Gamma_{jl}^s \partial_s$$

$$\text{i.e. } \nabla_{\partial_j} \nabla_{\partial_i} \partial_k = [\partial_j \Gamma_{ik}^s + \Gamma_{ik}^l \Gamma_{jl}^s] \partial_s$$

$$\text{Similarly, } \nabla_{\partial_i} \nabla_{\partial_j} \partial_k = [\partial_i \Gamma_{jk}^s + \Gamma_{jk}^l \Gamma_{il}^s] \partial_s$$

$$\text{and } \nabla_{[\partial_i, \partial_j]} \partial_k = 0$$

$$\Rightarrow R(\partial_i, \partial_j, \partial_k, \partial_l) = g_{sl} (\partial_j \Gamma_{ik}^s - \partial_i \Gamma_{jk}^s + \Gamma_{ik}^l \Gamma_{jl}^s + \Gamma_{jk}^l \Gamma_{il}^s)$$

$$\text{i.e. } R_{ijkl} = g_{sl} (\partial_j \Gamma_{ik}^s + \Gamma_{ik}^l \Gamma_{jl}^s - \partial_i \Gamma_{jk}^s - \Gamma_{jk}^l \Gamma_{il}^s) = F(g, \partial g, \partial^2 g)$$

Symmetries $\left\{ \begin{array}{l} R_{ijkl} + R_{jkil} + R_{kijl} = 0 \quad (\text{Bianchi}) \\ R_{ijkl} = -R_{jikl} = -R_{ijlk} = R_{klij} \end{array} \right.$

Q: How is the Riemann curvature tensor R related to the notion of "Gauss curvature" for surfaces in \mathbb{R}^3 ?

A: "sectional curvature"

Fix $p \in M$, and a 2-dim'l subspace $\sigma \in T_p M$

Defⁿ: Sectional curvature of σ at $p \in M$ is defined as

$$K_p(\sigma) := R(e_1, e_2, e_1, e_2)$$

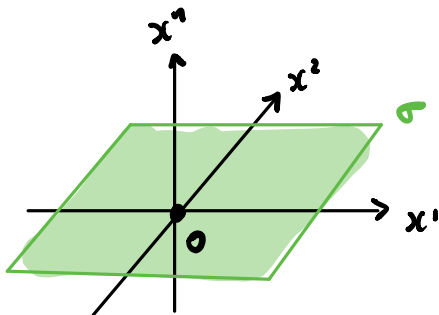
where $\{e_1, e_2\}$ o.n.b. for σ .

FACT: $K(\sigma)$ is "well-defined", i.e. indep. of the choice of o.n.b. $\{e_1, e_2\}$.

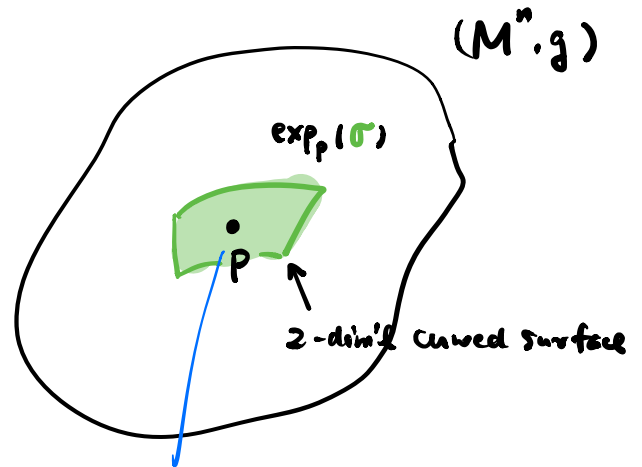
Geometric Meaning: $K_p(\sigma) \in \mathbb{R}$ measures the Gauss curvature at p of a "sub-surface" generated by σ in M .

geodesic normal coord.

$T_p M$



$\xrightarrow{\text{exp}_p}$



(Proof: Exercise!)

Gauss curvature of this sub-surface at $p = K_p(\sigma)$

We have the following algebraic fact.

Prop: Knowing all the sectional curvatures $K_p(\sigma)$ for all $\sigma \subset T_p M$ determines completely the Riem. curvature tensor R at p .

Proof: Idea: R_{ijij} ^{determines} R_{ijkl} using symmetries of R

Let $\{e_1, \dots, e_n\}$ be an O.N.B. for $T_p M$,

$$\sigma_{ij} := \text{span}\{e_i, e_j\} \subseteq T_p M, \quad i \neq j.$$

$$K(\sigma_{ij}) := R(e_i, e_j, e_i, e_j).$$

Using multi-linearity, only need to know $R(e_i, e_j, e_k, e_l)$, $i \neq j, k \neq l$.

Note: $R\left(\frac{e_i + e_k}{\sqrt{2}}, e_j, \frac{e_i + e_k}{\sqrt{2}}, e_j\right) = K(\text{span}\left\{\frac{e_i + e_k}{\sqrt{2}}, e_j\right\})$

BUT $R(e_i + e_k, e_j, e_i + e_k, e_j)$

$$= \underbrace{R(e_i, e_j, e_i, e_j)}_{K(\sigma_{ij})} + \underbrace{R(e_k, e_j, e_k, e_j)}_{K(\sigma_{kj})}$$

$$+ R(e_i, e_j, e_k, e_j) + R(e_k, e_j, e_i, e_j)$$

\ \ \ \ /
same

$$\Rightarrow R(e_i, e_j, e_k, e_j) = \text{"known"}$$

Note: $R\left(e_i, \frac{e_j + e_l}{\sqrt{2}}, e_k, \frac{e_j + e_l}{\sqrt{2}}\right) = \text{"known"}$

BUT $R(e_i, e_j + e_l, e_k, e_j + e_l)$

$$= \underbrace{R(e_i, e_j, e_k, e_j)}_{\text{"known"}} + \underbrace{R(e_i, e_l, e_k, e_l)}_{\text{"known"}} - R(e_j, e_k, e_i, e_l)$$

$$+ R(e_i, e_j, e_k, e_l) + R(e_i, e_l, e_k, e_j)$$

i.e. $R(e_i, e_j, e_k, e_l) - R(e_j, e_k, e_i, e_l) = \text{"known"}$

-) $R(e_k, e_i, e_j, e_l) - R(e_i, e_j, e_k, e_l) = \text{"known"}$

$2 R(e_i, e_j, e_k, e_l) + R(e_i, e_j, e_k, e_l) = \text{"known"}$

Cor: Let $C \in \mathbb{R}$ be a constant.

$K(\sigma) \equiv C \iff R(x, y, z, w) = C (\langle x, z \rangle \langle y, w \rangle - \langle y, z \rangle \langle x, w \rangle)$
 $\forall \sigma \in T_p M$

[check: $R(e_i, e_j, e_i, e_j) = C (\langle e_i, e_i \rangle \langle e_j, e_j \rangle - \langle e_j, e_i \rangle \langle e_i, e_j \rangle)$]

Ricci and scalar curvature

Let $\{e_1, \dots, e_n\}$ be an O.N.B. for $T_p M$.

Defⁿ: Ricci curvature $Ric(x, y) := \sum_{i=1}^n R(x, e_i, y, e_i)$

Scalar curvature $S := \sum_{i=1}^n Ric(e_i, e_i)$

FAST: well-defined, indep. of choice of O.N.B. $\{e_1, \dots, e_n\}$

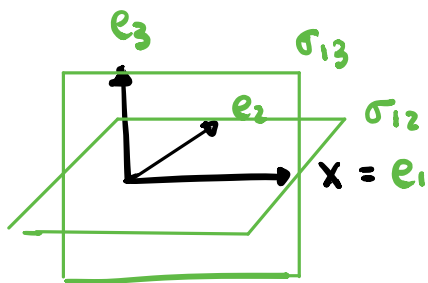
In local coord.,

$R_{ijkl} \xrightarrow{\text{"trace"}} R_{ik} := g^{jl} R_{ijkl} \xrightarrow{\text{"trace"}} R := g^{ik} R_{ik}$

Riem (0,4)-tensor Ricci (0,2)-tensor "symmetric" Scalar function

Geometric meaning: Ric & S are "averaged" sectional curvatures:

O.N.B. $\{X = e_1, e_2, \dots, e_n\}$



$$\text{Ric}(X, X) = \text{Ric}(e_1, e_1)$$

$$\begin{aligned} &:= \sum_{i=1}^n R(e_1, e_i, e_1, e_i) \\ &= \sum_{i=2}^n \underbrace{R(e_1, e_i, e_1, e_i)}_{k(\sigma_{1i})} \end{aligned}$$

Sum of sect. curv.
of planes through $e_1 = X$.

Similarly,
$$S := \sum_{i=1}^n \text{Ric}(e_i, e_i) = \sum_{i=1}^n \left(\sum_{j=1}^n R(e_i, e_j, e_i, e_j) \right)$$

$$= \sum_{i \neq j} R(e_i, e_j, e_i, e_j)$$

Sum of all sectional curv.

A Central Question in Riemannian Geometry

How does the Riem / Ric / Scalar curvatures affect the local/global geometry of (M^n, g) ?

E.g.) Gauss-Bonnet Thm:
$$\iint_S K \, da = 2\pi \chi(S).$$

Now, we digress a bit to talk about **covariant derivatives of general tensors**

Recall: A connection ∇ induces a covariant derivative for vector fields (i.e. $(1,0)$ -tensor):

Fix $X \in T(TM)$.

$$\begin{array}{ccc} \nabla_X : T(TM) & \longrightarrow & T(TM) \\ \downarrow & & \downarrow \\ Y & \longmapsto & \nabla_X Y \end{array}$$

Q: How to covariantly differentiate other tensors?

A: "Liebniz rule"

(i.e. (0,1)-tensors)

1-forms: $\omega \in \Omega^1(M) = T(T^*M) \rightsquigarrow \nabla_X \omega \in \Omega^1(M)$ defined as

$$(\nabla_X \omega)(Y) := X(\omega(Y)) - \omega(\nabla_X Y)$$

$\begin{array}{ccccccc} \nearrow & \uparrow & \uparrow & \nearrow & \uparrow & \searrow & \\ \text{v.f.} & \text{1-form} & \text{v.f.} & \text{v.f.} & \text{function} & \text{1-form} & \text{v.f.} \end{array}$

(1,1)-tensors: $\alpha \in T(T^*M) \rightsquigarrow \nabla_X \alpha \in T(T^*M)$ defined as

$$(\nabla_X \alpha)(Y, \omega) := X(\alpha(Y, \omega)) - \alpha(\nabla_X Y, \omega) - \alpha(Y, \nabla_X \omega)$$

Example 1: (M^n, g) g : (0,2)-tensor $\rightsquigarrow \exists!$ connection ∇

metric compatibility $\Leftrightarrow \nabla g \equiv 0$ i.e. $\nabla_X g \equiv 0 \quad \forall X$

why? $(\nabla_X g)(Y, Z) := X(g(Y, Z)) - g(\nabla_X Y, Z) - g(Y, \nabla_X Z)$

$\underbrace{\qquad\qquad\qquad}_{\nabla g \equiv 0} \quad \underbrace{\qquad\qquad\qquad}_{\text{metric compatibility}}$

Example 2: (Riem. curvature acting on 1-form)

Let $\omega \in \Omega^1(M)$. Define:

$$R(X, Y)\omega := \nabla_Y \nabla_X \omega - \nabla_X \nabla_Y \omega + \nabla_{[X, Y]}\omega$$

FACT: $(R(X, Y)\omega)(Z) = -\omega(R(X, Y)Z)$

Pf: $(R(x,y)w)(z)$

$$= (\nabla_y \nabla_x w - \nabla_x \nabla_y w + \nabla_{[x,y]} w)(z)$$

$$= Y((\nabla_x w)(z)) - (\nabla_x w)(\nabla_y z)$$

$$- X((\nabla_y w)(z)) + (\nabla_y w)(\nabla_x z)$$

$$+ [x,y](w(z)) - w(\nabla_{[x,y]} z)$$

$$= \underline{Y(X(w(z)) - w(\nabla_x z))} - \underline{X(w(\nabla_y z))} + w(\nabla_x \nabla_y z)$$

$$- \underline{X(Y(w(z)) - w(\nabla_y z))} + \underline{Y(w(\nabla_x z))} - w(\nabla_y \nabla_x z)$$

$$+ \underline{[x,y](w(z))} - w(\nabla_{[x,y]} z)$$

$$= -w(R(x,y), z).$$

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1st Bianchi identity: $R(x,y,z,w) + R(y,z,x,w) + R(z,x,y,w) = 0$

2nd Bianchi identity: $(\nabla_x R)(y,z,w,T) + (\nabla_y R)(z,x,w,T)$

(Pf: Exercise!)

$$+ (\nabla_z R)(x,y,w,T) = 0$$

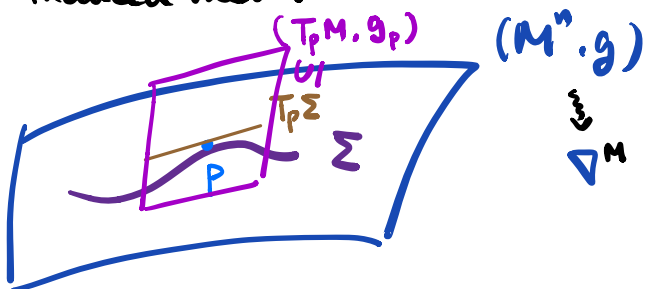
Submanifold theory

Goal: Generalize the classical theory for surfaces in \mathbb{R}^3 to submanifolds $\Sigma^k \subseteq (M^n, g)$

Defⁿ: An **isometric immersion** $F: (\Sigma^k, h) \rightarrow (M^n, g)$ is an immersion (as manifolds) s.t. $F^*g = h$

As far as local aspects are concerned, we can regard

$\Sigma^k \subseteq (M^n, g)$ and $g|_\Sigma$ induced metric as a k -dim'd embedded submfd



Note: $(\Sigma^k, g|_\Sigma)$ Riem mfd $\xrightarrow{\text{Fund Thm of R.G.}}$ $\exists!$ Riem connection ∇^Σ on Σ

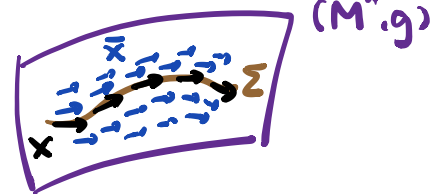
Q: How are the connections ∇^M and ∇^Σ related?

Recall: \exists 'canonical' orthogonal splitting: at each $p \in \Sigma$

$$T_p M = T_p \Sigma \oplus \underbrace{(T_p \Sigma)^\perp}_{\text{normal bundle } N_p \Sigma}$$

\leftarrow w.r.t g

$$\vec{v} = \vec{v}^T + \vec{v}^N$$



Thm: Let $X, Y \in T(T\Sigma)$. Then

$$\nabla_x^\Sigma Y = \left(\nabla_{\bar{X}}^M \bar{Y} \right)^T$$

where $\bar{X}, \bar{Y} \in T(TM)$ are 'extensions' of X, Y s.t. $\bar{X}|_\Sigma = X, \bar{Y}|_\Sigma = Y$